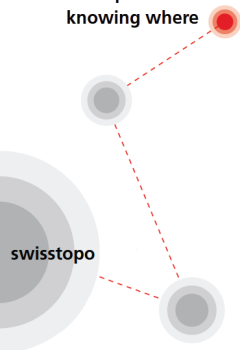




wissen wohin
savoir où
sapere dove
knowing where



Update of EUREF GNSS Analysis to Bernese SW V5.2: New Features and Impact on Results

S. Schaer, D. Ineichen, E. Brockmann



Bernese GNSS Software Version 5.2

- **Bernese GNSS Software Version 5.2** (BSW V5.2) was announced on 18 December 2012 in BSW Mail No. 310 (please be referred to www.bernese.unibe.ch >Support >BSW Mail Index and in particular to >Features)
- BSW V5.2 downloaded/installed via CVS access from the AIUB computer cluster. Other BSW versions (e.g. current development V5.3) would be accessible to us (PNAC), too.
- Changed data formats: satellite information, (multi-GNSS) PCV (phase center variations), CRD/VEL, station (STA) information; STD+, OBS+, NQ0+ (NEQ), TRO+, BLQ+.
- Special note: A number of BSW V5.2 changes originates from further developments, or ideas made at PNAC: improved baseline forming (SNGDIF), improved phase data preprocessing for short baselines (MAUPRP), GLONASS ambiguity resolution, “ISTPs” (GPSEST/ADDNEQ2), etc.



General Overview of Bernese SW Components and Update (Levels)

Bernese SW Components	BSW50□BSW52
Datapool (RINEX, orbits/ERPs/ION, <u>GEN</u>)	Linked/copied/ new
General (Perl) scripts (\$X/AUTO)	Copied& adjusted
BPE Processing Control Files (\$U/PCF)	Copied& extended
BPE Perl scripts (\$U/SCRIPT)	Copied& adjusted
INP panels (\$U/OPT)	Copied& updated & adjusted
BSW source code and <i>executables</i> (\$FG)	New (few minor changes)
REF(erence) files (CRD/VEL, STA, <u>PCV</u> , BLQ)	Converted (...)
Other scripts and tools	

- Updated FES2004.BLQ (ocean loading correction tables).
- Hatanaka RINEX decompression/compression software to be updated from V4.0.3 (2007-06-21) to V4.0.5 (2012-07-18) (see: <http://terras.gsi.go.jp/ja/crx2rnrx.html>)



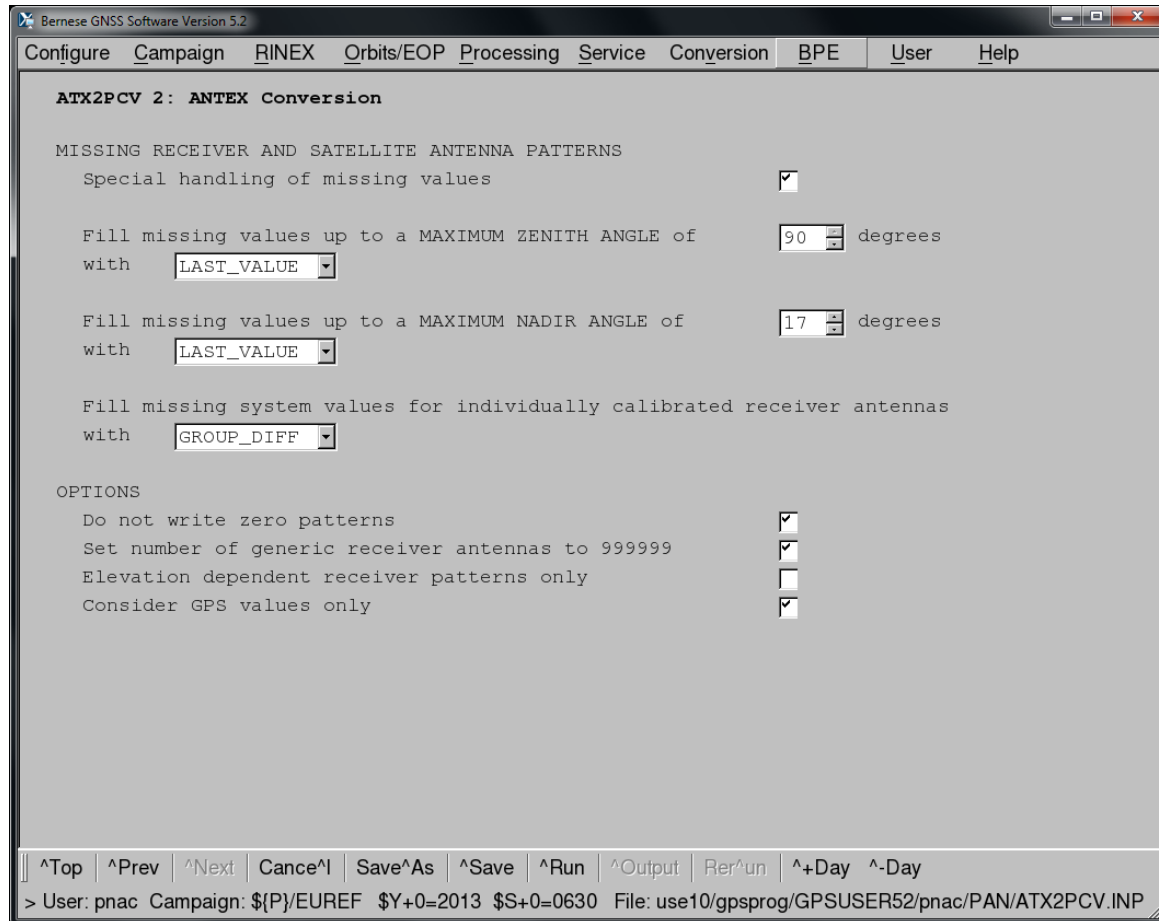
GNSS PCV Information and ATX2PCV: From PHAS_LPT.* (BSW50) to PCV_LPT.* (BSW52)

- 5 (actually 6) BSW50 (GPS) PCV files are maintained at PNAC:
 - I01: IGS01, relative, group calibrations (4 000 – 9000 lines)
 - C01: IGS01, relative, group plus all PNAC individual calibrations
 - I08: IGS08, absolute, group calibrations (30 000 – 45 000 lines)
 - C08: IGS08, absolute, group plus PNAC individual calibrations (52 000 – 89 000 lines)
 - E08: IGS08/EPNC, absolute, group plus EPN individual calibrations
 - B08: “GLONASS-specific C08”
- ANTEX data sources considered are:
 - I01 (GPS): IGS_01, relative group calibrations (1 300 lines)
 - I08 (GNSS): IGS08_1735, absolute group calibrations (40 000 lines)
 - E08 (GNSS): EPNC, absolute individual calibrations (19 000 lines)
 - Plus a number of (primarily AGNES-specific) ATX files
- ANTEX-to-PCV convertor: ATX2PCV V5.2 is the replacement for PHCCNV V5.0:
 - New **multi-GNSS-capable** PCV data format
 - Calibration method and calibration date is now considered (– SINEX code)
 - Additional converter options are available, such as ...



ATX2PCV

- GPS_VALUES/GROUP_VALUES/GROUP_DIFF
- “GPS-only”





Listing of Possible System/SINEX/Method-Combinations in PCV_LPT.E08:

SYS	SINEX	METHOD	DATE
*	*****	*****	*****
G	EPNC	CHAMBER	
G	EPNC	FIELD	
G	EPNC	ROBOT	
G	IGS08		
G	IGS08_1734	ADOPTED from NONE	
G	IGS08_1734	CONVERTED	
G	IGS08_1734	COPIED	
G	IGS08_1734	FIELD	
G	IGS08_1734	ROBOT	
G	IGS08	FIXED	
R	EPNC	ADOPTED from GPS	
R	EPNC	CHAMBER	
R	EPNC	ROBOT	
R	IGS08		
R	IGS08_1734	ADOPTED from GPS	
R	IGS08_1734	ADOPTED from group	
R	IGS08_1734	ADOPTED from NONE	
R	IGS08_1734	COPIED	
R	IGS08_1734	ROBOT	
R	IGS08	FIXED	



METH(od) Records as Extracted from epnc(_08).atx:

CHAMBER	AMK BONN	1	01-Feb-11	METH / BY / # / DATE
CHAMBER	AMK BONN	1	08-Mar-12	METH / BY / # / DATE
CHAMBER	AMK BONN	1	14-Jul-10	METH / BY / # / DATE
CHAMBER	AMK BONN	1	2010_10_07	METH / BY / # / DATE
ROBOT	Geo++ GmbH	1	2000-05-28	METH / BY / # / DATE
ROBOT	Geo++ GmbH	1	2000-10-30	METH / BY / # / DATE
ROBOT	Geo++ GmbH	1	2002-03-11	METH / BY / # / DATE
...				
ROBOT	Geo++ GmbH	2	2008-04-15	METH / BY / # / DATE
ROBOT	Geo++ GmbH	2	2008-04-16	METH / BY / # / DATE
ROBOT	Geo++ GmbH	2	2008-04-17	METH / BY / # / DATE
ROBOT	IfE	1	2008-05-20	METH / BY / # / DATE
FIELD	LWa	1	06.02.2007	METH / BY / # / DATE
ROBOT	SenStadt BERLIN	1	2007-05-18	METH / BY / # / DATE
ROBOT	SenStadt BERLIN	1	2007-07-09	METH / BY / # / DATE
ROBOT	SenStadt BERLIN	1	2007-09-14	METH / BY / # / DATE
...				
ROBOT	SenStadt BERLIN	1	2007-11-13	METH / BY / # / DATE
ROBOT	SenStadt BERLIN	1	2008-02-19	METH / BY / # / DATE
ROBOT	SenStadt_BERLIN	12	2010-02-17	METH / BY / # / DATE

EPNC

SINEX CODE



Characteristics of Various EUREF GNSS Analysis Solutions Computed at PNAC (for Comparison/Validation Purposes)

Solution ID (code)	SW version	Tropo/gradients	GLO PCV	HO Iono & 3 SPs	IERS conventions & other models
Old (0)	BSW V5.0+	NMF/TILTING	No	No	IERS20000
New (1)	BSW V5.2	NMF/TILTING	No	No/ZERO	IERS20001
A (2A)	BSW V5.2	NMF/TILTING	No	No	IERS20102
B (2B)	BSW V5.2	GMF/CHENHER	No	No	IERS20102
C (2C)	BSW V5.2	GMF/CHENHER	Yes	No	IERS20102
D (2D)	BSW V5.2	GMF/CHENHER	Yes	No/ZERO	IERS20102
Last (2)	BSW V5.2	GMF/CHENHER	Yes	Yes/ONE	IERS20102
VMF	BSW V5.2	VMF/CHENHER	Yes	Yes	IERS20102
COE	BSW V5.3	VMF/CHENHER	Yes	Yes/ONE	IERS20103

0DE200, JGM3, IERS2000.SUB, IAU2000.NUT, old BLQ, red. GLO AR □ SNGDIF bonus, MAUPRP auto

1DE405, JGM3, IERS2000.SUB, IAU2000.NUT, old BLQ, red. GLO AR □ HOI SPs, ISTPs

2DE405, EGM2008_SMALL, IERS2010XY.SUB, IAU2000R06.NUT, updated BLQ, GPS QCPB*, CMC/ATL, red. GLO AR, MAUPRP iono

3DE405, EGM2008_SMALL, IERS2010XY.SUB, IAU2000R06.NUT, updated BLQ, GPS QCPB, CMC/ATL, MW & full GLO AR, MAURPR iono



EUREF Subnetwork as Considered at swisstopo's PNAC

Data of 51 stations processed for day 063, 2013 (week 1730):



GM2 2013 Apr 18 11:54:04



Impact of SW/Model Updates/Changes as Summarized for North, East, Up, Total RMS (mm), Scale (ppm) (Based on 7-Parameter Helmert Transformations):

BSW50-BSW52 (as close as possible):

P1_ 0-N:	0.08	0.09	0.15	0.11	-0.00099	□ P1_ = Preliminary, ambiguity-float GNSS solution
F1_ 0-N:	0.16	0.10	0.14	0.14	-0.00098	□ F1_ = Final, ambiguity-fixed GNSS solution
F1A 0-N:	0.08	0.09	0.12	0.10	-0.00096	□ F1A = Final, ambiguity-fixed GPS-only solution

IERS2000-IERS2010 and other minor updates:

F1_ N-A:	0.09	0.30	0.50	0.34	-0.00035
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Troposphere/gradients:

F1_ A-B:	0.15	0.16	0.65	0.40	-0.00098
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GLONASS PCV:

F1_ B-C:	0.21	0.17	1.42	0.85	-0.00014
F1A B-C:	0.00	0.00	0.00	0.00	0.00000

Higher-order ionosphere (deactivated at NEQ level):

F1_ C-D:	0.00	0.00	0.00	0.00	0.00000
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Higher-order ionosphere:

F1_ D-L:	0.05	0.02	0.02	0.03	0.00013
----------	------	------	------	------	---------

Overall impact of all BSW52 model updates:

P1_ N-L:	0.27	0.24	1.98	1.18	-0.00194
F1_ N-L:	0.24	0.37	1.75	1.06	-0.00134

BSW50-BSW52 (latest models):

P1_ 0-L:	0.26	0.27	2.01	1.20	-0.00292
F1_ 0-L:	0.30	0.37	1.76	1.07	-0.00233



Impact of SW/Model Updates/Changes as Summarized for North, East, Up, Total RMS (mm), Scale (ppm) (Based on 7-Parameter Helmert Transformations) (cont.):

BSW50(Old) - BSW52 (VMF) :

F1_ 0-V: 0.37 0.42 2.76 1.65 -0.00265

F1A 0-V: 0.32 0.36 2.20 1.32 -0.00252

BSW52(New) - BSW52 (VMF) :

F1_ N-V: 0.37 0.42 2.72 1.63 -0.00167

F1A N-V: 0.30 0.34 2.18 1.30 -0.00157

BSW52(Last) - BSW52 (VMF) : From GMF to VMF :

F1_ L-V: 0.17 0.18 1.67 0.99 -0.00032

F1A L-V: 0.16 0.17 1.60 0.95 -0.00033



“1ppb” Issue

BSW50-BSW52, with Shapiro, with Hardisp:

F1A 0-N: 0.08 0.08 0.09 0.08 -0.00090

BSW50-BSW52, with Shapiro, without Hardisp:

F1A 0-N: 0.08 0.08 0.09 0.08 -0.00089

BSW50-BSW52, without Shapiro, without Hardisp:

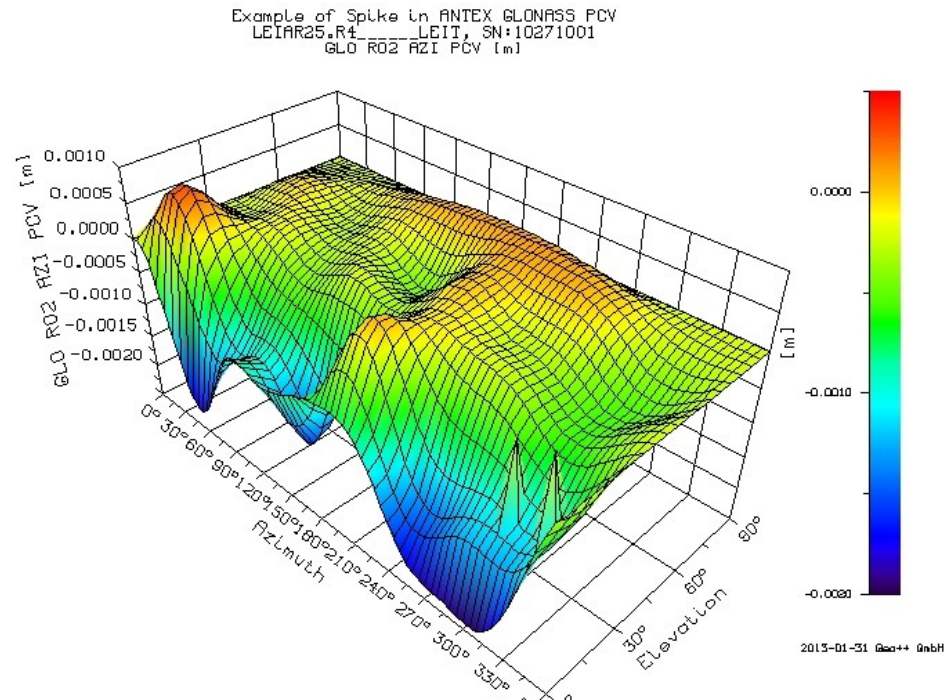
F1A 0-N: 0.08 0.08 0.08 0.08 +0.00004

Many thanks to R. Dach (AIUB) for doing the corresponding test analyses (at swisstopo).



Remark on “Spikes Removed From GLONASS PCV Calibrations”

- “Spikes” removed in IGS GNSS (GLONASS) PCV model with update from IGS08_1731 to IGS08_1734 (nominally to be considered as of 31 March 2013)
- See also: www.geopp.de >The company >News:





Remark on “Spikes Removed From GLONASS PCV Calibrations” (cont.)

IGSFINAL/STA/F1_13090.CRD: GNSS

		RMS / COMPONENT			0.00	0.00	0.01		
		MEAN			0.00	0.00	0.00		
		MIN			-0.01	-0.01	-0.02		
		MAX			0.02	0.01	0.02		

EPNFINAL/STA/F1_13069.CRD: GNSS

		RMS / COMPONENT			0.00	0.00	0.00		
		MEAN			-0.00	-0.00	0.00		
		MIN			-0.01	-0.01	-0.01		
		MAX			0.01	0.01	0.01		

EPNFINAL/STA/F1A13069.CRD: GPS-only

		RMS / COMPONENT			0.00	0.00	0.00		
		MEAN			0.00	0.00	0.00		
		MIN			0.00	0.00	0.00		
		MAX			0.00	0.00	0.00		

EPNFINAL/STA/F1B13069.CRD: GLONASS-only

		RMS / COMPONENT			0.01	0.01	0.01		
		MEAN			-0.00	-0.00	0.00		
		MIN			-0.01	-0.03	-0.03		
		MAX			0.01	0.02	0.03		

Given North/East/Up values are expressed in units of mm.



CPU Time Consumption

- GPSEST (just an issue with the Lahey compiler used at PNAC):
 - Considerably increased CPU time consumption for GPSEST
 - turned out to be in subroutines VECTR_P, PRITR_P, PRIEST
 - correction in subroutine TRPVEC:
REAL*8 XXX(*), ANOR(*) □ REAL*8 XXX(:), ANOR(:)
 - EUREF:
 - CPU time reduction from 8.5 to 4 min (approx. 2x)
 - AGNES:
 - CPU time reduction from 150 to 35 min (approx. 4-5x)
- ADDNEQ2:
 - MULTI_A (PNAC's multi-year solution using ADDNEQ2):
 - CPU time reduction from 4500 to 400 sec (9% or 11x)
 - specific option to be changed: HELMERT □ HLM_ALL
 - BSW52 results are *consistent* with BSW50 results
- Helpful BPE processing summary concerning CPU time consumption (see: BPE/EUREF.OUT,).

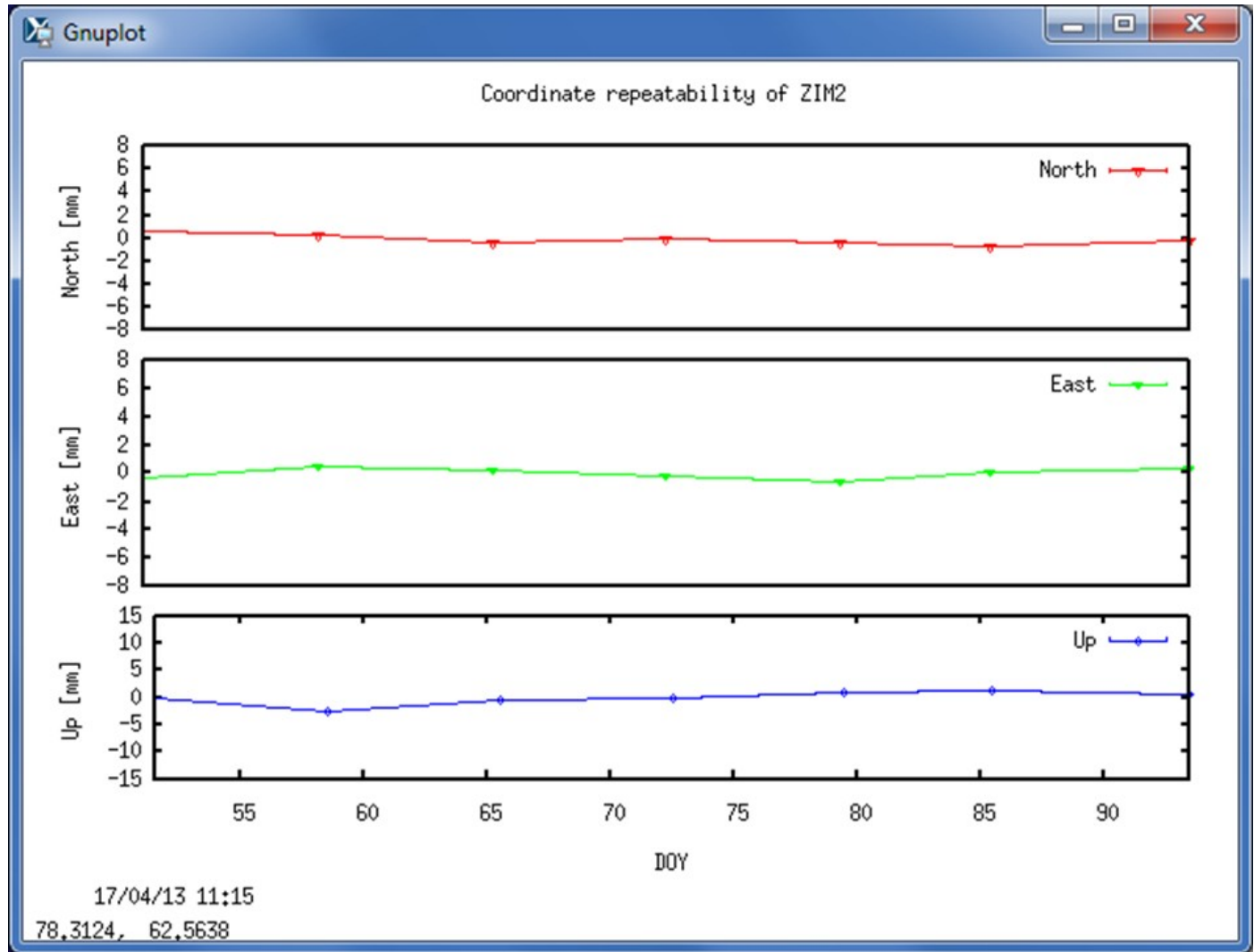


Summary and Conclusions

- The impact of various model updates could be demonstrated (gradually).
- The detailed study comparing the BSW V5.0/V5.2 results revealed a few problems (e.g. RXOBV3, ATX2PCV).
- First BSW V5.2 EUREF results (for GPS week 1731) could be submitted on 16 April 2013 by PNAC (addressed as “LPT”).
- Switching progress delayed due to two issues:
 - ATX2PCV
 - “1ppb”--finally attributed to the correction of the Shapiro effect
- Updated version of ATX2PCV may be expected soon (at least a first version covering commonly used advanced applications).



EUREF: 3 Weeks (BSW50) / 4 Weeks (BSW52)





Next Steps and Outlook

- Update accordingly: AMET, AGNES, AUTOCAMP, PPP.
- Further develop a refined, “repro”-capable RNX2SNX V5.2 BPE procedure for:
 - AGNES/EUREF reprocessing planned for 2013
 - eventual replacement of current BPE procedures
- Key words: Melbourne-Wübbena AR, full GLONASS AR, new GNSS observation selection (OBS.SEL) and proper handling of potential GPS quarter-cycle phase biases, VMF/APL, “SNX_LOOP”, “FIX_CHK”, improved RESRMS/RESCHK.



Scale With Respect to EUREF Combined Solution

